

BATTLEFIELD 3

DirectX 11 Rendering in Battlefield 3

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Agenda

Overview

Feature:

- › Deferred Shading
- › Compute Shader Tile-Based Lighting
- › Terrain Displacement Mapping
- › Direct Stereo 3D rendering

Quality:

- › Antialiasing: MSAA
- › Antialiasing: FXAA
- › Antialiasing: SRAA
- › Transparency Supersampling

Performance:

- › Instancing
- › Parallel dispatch
- › Multi-GPU
- › Resource Streaming

Conclusions

Q & A

OVERVIEW



Battlefield 3

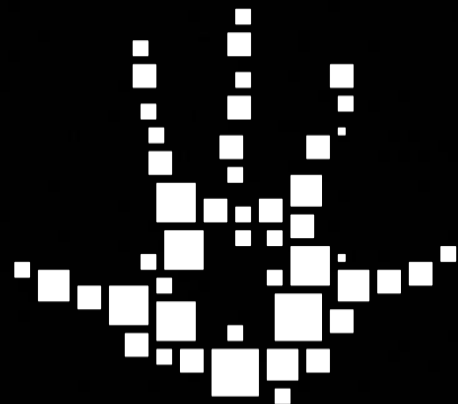
- › FPS
- › Fall 2011
- › DX11, Xbox 360 and PS3
- › Frostbite 2 engine

BATTLEFIELD 3



Frostbite 2

- › Developed for Battlefield 3 and future DICE/EA games
- › Massive focus on creating simple to use & powerful workflows
- › Major pushes in animation, destruction, streaming, rendering, lighting and landscapes



FROSTBITE™2



DX11

DX11 API only

- › Requires a DX10 or DX11 GPUs
- › Requires Vista SP1 or Windows 7
- › No Windows XP!

Why?

- › CPU performance win
- › GPU performance & quality win
- › Ease of development - no legacy
- › Future proof

BF3 is a *big* title - will drive OS & HW adoption

- › Which is good for *your* game as well! 😊



Options for rendering

Switched to Deferred Shading in FB2

- › Rich mix of Outdoor + Indoor + Urban environments in BF3
- › Wanted *lots* more light sources

Why not Forward Rendering?

- › Light culling / shader permutations not efficient for us
- › Expensive & more difficult decaling / destruction masking

Why not Light Pre-pass?

- › 2x geometry pass too expensive on both CPU & GPU for us
- › Was able to generalize our BRDF enough to just a few variations
- › Saw major potential in full tile-based deferred shading

See also:

- › Nicolas Thibieroz's talk "Deferred Shading Optimizations"



Deferred Shading

Weaknesses with traditional deferred lighting/shading:

- › Massive overdraw & ROP cost when having lots of *big* light sources
- › Expensive to have multiple per-pixel materials in light shaders
- › MSAA lighting can be slow (non-coherent, extra BW)

FEATURES



Tile-based Deferred Shading

1. Divide screen into tiles and determine which lights affects which tiles

2. Only apply the visible light sources on pixels

- › Custom shader with multiple lights
- › Reduced bandwidth & setup cost

How can we do this best in DX11?

	1			1	
1	1	1		1	
1	1	1	4	4	1
1	3	3		2	1
1	8	12		2	1
17	16	19		2	1
20	18	23		2	1
1		2		2	1
2		2		2	1
1	1	1		2	1
					1
					1

Lighting with Compute Shader

Tile-based Deferred Shading using Compute Shaders

Primarily for analytical light sources

- › Point lights, cone lights, line lights
- › No shadows
- › Requires Compute Shader 5.0



Hybrid Graphics/Compute shading pipeline:

- › Graphics pipeline rasterizes gbuffers for opaque surfaces
- › Compute pipeline uses gbuffers, culls lights, computes lighting & combines with shading
- › Graphics pipeline renders transparent surfaces on top

CS requirements & setup

1 thread per pixel, 16x16 thread groups (aka tile)

Input: gbuffers, depth buffer & list of lights

Output: fully composited & lit HDR texture

```
Texture2D<float4> gbufferTexture0 : register(t0);  
Texture2D<float4> gbufferTexture1 : register(t1);  
Texture2D<float4> gbufferTexture2 : register(t2);  
Texture2D<float4> depthTexture : register(t3);
```

```
RWTexture2D<float4> outputTexture : register(u0);
```

```
#define BLOCK_SIZE 16  
[numthreads(BLOCK_SIZE,BLOCK_SIZE,1)]  
void csMain(  
    uint3 groupId : SV_GroupID,  
    uint3 groupThreadId : SV_GroupThreadID,  
    uint groupIdIndex: SV_GroupIndex,  
    uint3 dispatchThreadId : SV_DispatchThreadID)  
{  
    ...  
}
```

Normal



Roughness



Diffuse Albedo



Specular Albedo

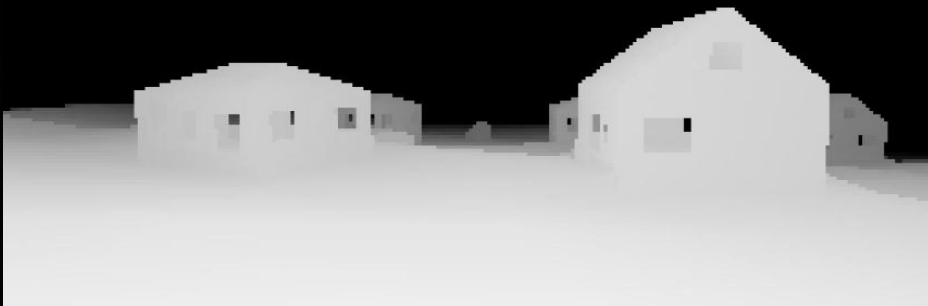


CS steps 1-2

1. Load gbuffers & depth

2. Calculate min & max z in threadgroup / tile

- › Using InterlockedMin/Max on groupshared variable
- › Atomics only work on ints 😞
- › Can cast float to int (z is always +)



```
groupshared uint minDepthInt;  
groupshared uint maxDepthInt;
```

```
// --- globals above, function below -----
```

```
float depth =  
    depthTexture.Load(uint3(texCoord, 0)).r;  
uint depthInt = asuint(depth);
```

```
minDepthInt = 0xFFFFFFFF;  
maxDepthInt = 0;  
GroupMemoryBarrierWithGroupSync();
```

```
InterlockedMin(minDepthInt, depthInt);  
InterlockedMax(maxDepthInt, depthInt);
```

```
GroupMemoryBarrierWithGroupSync();  
float minGroupDepth = asfloat(minDepthInt);  
float maxGroupDepth = asfloat(maxDepthInt);
```

CS step 3 – Culling

Determine visible light sources for each tile

- › Cull all light sources against tile frustum

Input (global):

- › Light list, frustum & SW occlusion culled

Output (per tile):

- › # of visible light sources
- › Index list of visible light sources

	Lights	Indices
Global list	1000+	0 1 2 3 4 5 6 7 8 ..
Tile visible list	~0-40+	0 2 5 6 8 ..

Per-tile visible light count
(black = 0 lights, white = 40)



CS step 3 – Impl

3a. Each thread switches to process lights instead of pixels

- › Wow, parallelism switcharoo!
- › 256 light sources in parallel
- › Multiple iterations for >256 lights

3b. Intersect light and tile

- › Multiple variants – accuracy vs perf
- › Tile min & max z is used as a "depth bounds" test

3c. Append visible light indices to list

- › Atomic add to threadgroup shared memory
- › "inlined stream compaction"

3d. Switch back to processing pixels

- › Synchronize the thread group
- › We now know which light sources affect the tile

```
struct Light {  
    float3 pos; float sqrRadius;  
    float3 color; float invSqrRadius;  
};  
int lightCount;  
StructuredBuffer<Light> lights;
```

```
groupshared uint visibleLightCount = 0;  
groupshared uint visibleLightIndices[1024];
```

```
// --- globals above, cont. function below ---
```

```
uint threadCount = BLOCK_SIZE*BLOCK_SIZE;  
uint passCount = (lightCount+threadCount-1) / threadCount;
```

```
for (uint passIt = 0; passIt < passCount; ++passIt)  
{  
    uint lightIndex = passIt*threadCount + groupIndex;
```

```
    // prevent overrun by clamping to a last "null" light  
    lightIndex = min(lightIndex, lightCount);
```

```
    if (intersects(lights[lightIndex], tile))  
    {
```

```
        uint offset;  
        InterlockedAdd(visibleLightCount, 1, offset);  
        visibleLightIndices[offset] = lightIndex;
```

```
    }
```

```
GroupMemoryBarrierWithGroupSync();
```

CS deferred shading final steps

4. For each pixel, accumulate lighting from visible lights

- › Read from tile visible light index list in groupshared memory

5. Combine lighting & shading albedos

- › Output is non-MSAA HDR texture
- › Render transparent surfaces on top

```
float3 color = 0;

for (uint lightIt = 0; lightIt < visibleLightCount; ++lightIt)
{
    uint lightIndex = visibleLightIndices[lightIt];
    Light light = lights[lightIndex];

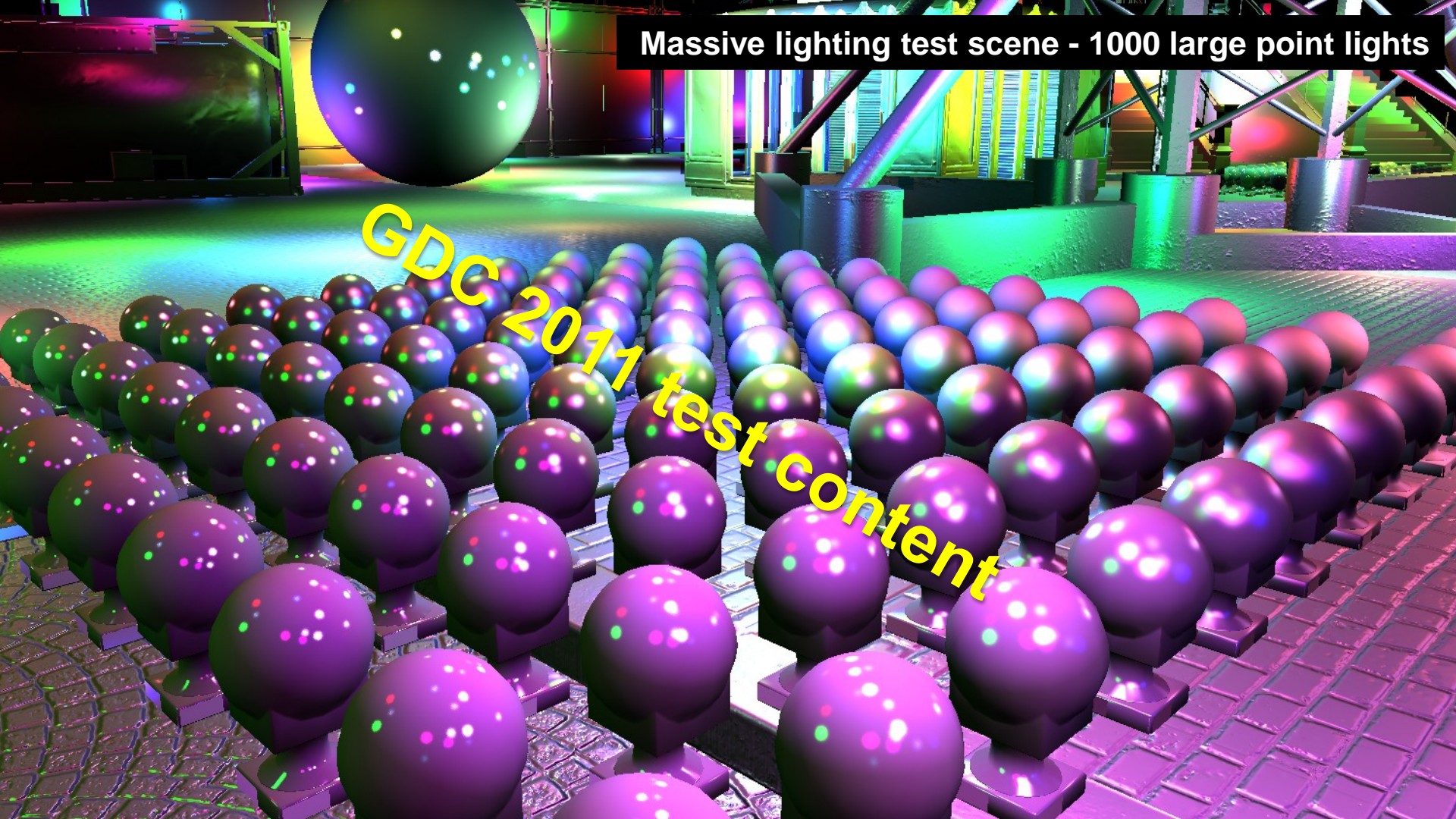
    color += diffuseAlbedo * evaluateLightDiffuse(light, gbuffer);
    color += specularAlbedo * evaluateLightSpecular(light, gbuffer);
}
```

Computed lighting



Massive lighting test scene - 1000 large point lights

GDC 2011 test content



MSAA Compute Shader Lighting

Only edge pixels need full per-sample lighting

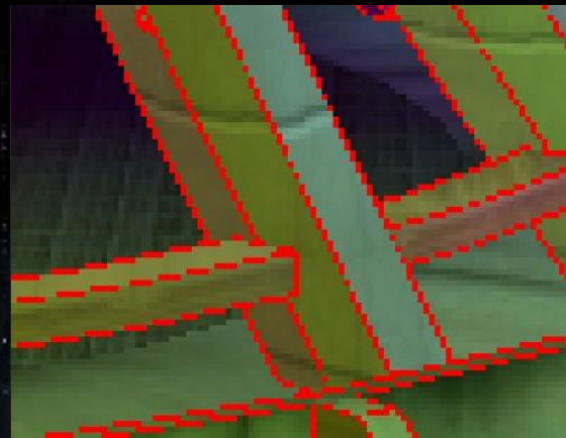
- › But edges have bad screen-space coherency! Inefficient

Compute Shader can build efficient coherent pixel list

- › Evaluate lighting for each pixel (sample 0)
- › Determine if pixel requires per-sample lighting
- › If so, add to atomic list in shared memory
- › When all pixels are done, synchronize
- › Go through and light sample 1-3 for pixels in list

Major performance improvement!

- › Described in detail in [Lauritzen10]



Terrain rendering



Terrain rendering

Battlefield 3 terrains

- › Huge area & massive view distances
- › Dynamic destructible heightfields
- › Procedural virtual texturing
- › Streamed heightfields, colormaps, masks
- › Full details at a later conference



We stream in source heightfield data at close to pixel ratio

- › Derive high-quality per-pixel normals in shader

How can we increase detail even further on DX11?

- › Create better silhouettes and improved depth
- › Keep small-scale detail (dynamic craters & slopes)



GDC 2011 pre-alpha

Normal mapped terrain

GDC 2011 pre-alpha

Displacement mapped terrain

GDC 2011 pre-alpha

Terrain Displacement Mapping

Straight high-res heightfields, no procedural detail

- › Lots of data in the heightfields
- › Pragmatic & simple choice
- › No changes in physics/collisions
- › No content changes, artists see the true detail they created

Uses DX11 fixed edge tessellation factors

- › Stable, no swimming vertices
- › Though can be wasteful
- › Height morphing for streaming by fetching 2 heightfields in domain shader & blend based on patch CLOD factor

More work left to figure optimal tessellation scheme for our use case

Stereo 3D rendering in DX11

Nvidia's 3D Vision drivers is a good and *almost* automatic stereo 3D rendering method

- › But only for forward rendering, doesn't work with deferred shading
- › Or on AMD or Intel GPUs
- › Transparent surfaces do not get proper 3D depth

We instead use *explicit* 3D stereo rendering

- › Render unique frame for each eye
- › Works with deferred shading & includes all surfaces
- › Higher performance requirements, 2x draw calls

Works with *Nvidia's 3D Vision* and *AMD's HD3D*

- › Similar to OpenGL quad buffer support
- › Ask your friendly IHV contact how

PERFORMANCE



Instancing

Draw calls can still be major performance bottleneck

- › Lots of materials / lots of variation
- › Complex shadowmaps
- › High detail / long view distances
- › Full 3D stereo rendering

Battlefield have lots of use cases for heavy instancing

- › Props, foliage, debris, destruction, mesh particles



*Richard Huddy:
"Batch batch batch!"*



Batching submissions is still important, just as before!

Instancing in DirectX

DX9-style stream instancing is good, but restrictive

- › Extra vertex attributes, GPU overhead
- › Can't be (efficiently) combined with skinning
- › Used primarily for tiny meshes (particles, foliage)

DX10/DX11 brings support for shader *Buffer* objects

- › Vertex shaders have access to *SV_InstanceID*
- › Can do completely arbitrary loads, not limited to fixed elements
- › Can support per-instance arrays and other data structures!

Let's rethink how instancing can be implemented..

Instancing data

Multiple object types

- › Rigid / skinned / composite meshes

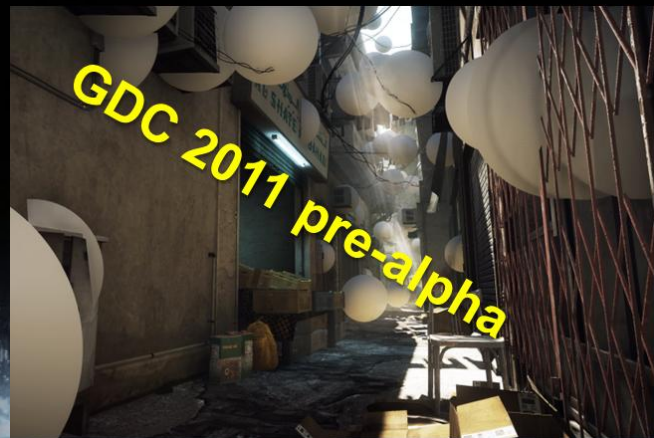
Multiple object lighting types

- › Small/dynamic: light probes
- › Large/static: light maps

Different types of instancing data we have

- › Transform `float4x3`
- › Skinning transforms `float4x3 array`
- › SH light probe `float4 x 4`
- › Lightmap UV scale/offset `float4`

Let's pack all instancing data into single big buffer!



Instantiating example: transform + SH

```
Buffer<float4> instanceVectorBuffer : register(t0);
```

```
cbuffer a
{
    float g_startVector;
    float g_vectorsPerInstance;
}
```

```
VsOutput main(
    // ....
```

```
    uint instanceId : SV_InstanceId)
{
```

```
    uint worldMatrixVectorOffset = g_startVector + input.instanceId * g_vectorsPerInstance + 0;
    uint probeVectorOffset       = g_startVector + input.instanceId * g_vectorsPerInstance + 3;
```

```
    float4 r0 = instanceVectorBuffer.Load(worldMatrixVectorOffset + 0);
    float4 r1 = instanceVectorBuffer.Load(worldMatrixVectorOffset + 1);
    float4 r2 = instanceVectorBuffer.Load(worldMatrixVectorOffset + 2);
```

```
    float4 lightProbeShR = instanceVectorBuffer.Load(probeVectorOffset + 0);
    float4 lightProbeShG = instanceVectorBuffer.Load(probeVectorOffset + 1);
    float4 lightProbeShB = instanceVectorBuffer.Load(probeVectorOffset + 2);
    float4 lightProbeShO = instanceVectorBuffer.Load(probeVectorOffset + 3);
```

```
    // ....
}
```

Instancing example: skinning

```
half4 weights = input.boneWeights;  
int4 indices = (int4)input.boneIndices;
```

```
float4 skinnedPos = mul(float4(pos,1), getSkinningMatrix(indices[0])).xyz * weights[0];  
skinnedPos += mul(float4(pos,1), getSkinningMatrix(indices[1])).xyz * weights[1];  
skinnedPos += mul(float4(pos,1), getSkinningMatrix(indices[2])).xyz * weights[2];  
skinnedPos += mul(float4(pos,1), getSkinningMatrix(indices[3])).xyz * weights[3];
```

```
// ...
```

```
float4x3 getSkinningMatrix(uint boneIndex)  
{  
    uint vectorOffset = g_startVector + instanceId * g_vectorsPerInstance;  
    vectorOffset += boneIndex*3;  
    float4 r0 = instanceVectorBuffer.Load(vectorOffset + 0);  
    float4 r1 = instanceVectorBuffer.Load(vectorOffset + 1);  
    float4 r2 = instanceVectorBuffer.Load(vectorOffset + 2);  
    return createMat4x3(r0, r1, r2);  
}
```

Instancing benefits

Single draw call per object *type* instead of per *instance*

- › Minor GPU hit for big CPU gain

Instancing does not break when skinning parts

- › More deterministic & better overall performance

End result is typically 1500-2000 draw calls

- › Regardless of how many object *instances* the artists place!
- › Instead of 3000-7000 draw calls in some heavy cases

Parallel Dispatch in Theory

Great key DX11 feature!

- › Improve performance by scaling dispatching to D3D to more cores
- › Reduce frame latency

How we use it:

- › DX11 deferred context per HW thread
- › Renderer builds list of all draw calls we want to do for each rendering "layer" of the frame
- › Split draw calls for each layer into chunks of ~256
- › Dispatch chunks in parallel to the deferred contexts to generate command lists
- › Render to immediate context & execute command lists
- › Profit! *

* but theory != practice

Parallel Dispatch in Practice

Still no performant drivers available for our use case 😞

- › Have waited for 2 years and still are
- › Big driver codebases takes time to refactor
- › IHVs vs Microsoft quagmire
- › Heavy driver threads collide with game threads

quagmire ['kwæg, maɪə 'kwɒg-]n

1. (Earth Sciences / Physical Geography) a soft wet area of land that gives way under the feet; bog
2. an awkward, complex, or embarrassing situation

How it should work (an utopia?)

- › Driver does not create any processing threads of its own
- › Game submits workload in parallel to multiple deferred contexts
- › Driver make sure almost all processing required happens on the draw call on the deferred context
- › Game dispatches command list on immediate context, driver does absolute minimal work with it

Still good to design engine for + instancing is great!

Resource streaming

Even with modern GPUs with lots of memory, resource streaming is often required

- › Can't require 1+ GB graphics cards
- › BF3 levels have much more than 1 GB of textures & meshes
- › Reduced load times

But creating & destroying DX resources in-frame has never been a good thing

- › Can cause non-deterministic & large driver / OS stalls ☹️
- › Has been a problem for a very long time in DX
- › About time to fix it



DX11 Resource Streaming

Have worked with Microsoft, Nvidia & AMD to make sure we can do stall free async resource streaming of GPU resources in DX11

- › Want neither CPU nor GPU perf hit
- › Key foundation: DX11 concurrent creates

```
D3D11_FEATURE_DATA_THREADING threadingCaps;  
  
FB_SAFE_DX(m_device->CheckFeatureSupport(  
    D3D11_FEATURE_THREADING,  
    &threadingCaps, sizeof(threadingCaps)));  
  
if (threadingCaps.DriverConcurrentCreates)
```

Resource creation flow:

- › Streaming system determines resources to load (texture mipmaps or mesh LODs)
- › Add up DX resource creation on to queue on our own separate low-priority thread
- › Thread creates resources using initial data, signals streaming system
- › Resource created, game starts using it

Enables async stall-free DMA in drivers!

Resource destruction flow:

- › Streaming system deletes D3D resource
- › Driver keeps it internally alive until GPU frames using it are done. NO STALL!

Multi-GPU

Efficiently supporting **Crossfire** and **SLI** is important for us

- › High-end consumers expect it
- › IHVs expect it (and can help!)
- › Allows targeting higher-end HW then currently available during dev

AFR is easy: Do not reuse GPU resources from previous frame!

- › UpdateSubResource is easy & robust to use for dynamic resources, but not ideal

All of our playtests run with exe named AFR-FriendlyD3D.exe

- › Disables all driver AFR synchronization workarounds
- › Rather find corruption during dev then have bad perf
- › ForceSingleGPU.exe is also useful to track down issues

QUALITY



Antialiasing

Reducing aliasing is one of our key visual priorities

- › Creates a more smooth gameplay experience
- › Extra challenging goal due to deferred shading

We use multiple methods:

- › MSAA – Multisample Antialiasing
- › FXAA – Fast Approximate Antialiasing
- › SRAA – Sub-pixel Reconstruction Antialiasing
- › TSAA – Transparency Supersampling Antialiasing

Aliasing 😞



MSAA

Our solution:

- › Deferred geometry pass renders with MSAA (2x, 4x or 8x)
- › Light shaders evaluate per-sample (when needed), averages the samples and writes out per-pixel
- › Transparent surfaces rendered on top without MSAA

1080p gbuffer+z with 4x MSAA is 158 MB

- › Lots of memory and lots of bandwidth 😞
- › Could be tiled to reduce memory usage
- › Very nice quality though 😊

Our (overall) highest quality option

- › But not fast enough for more GPUs
- › Need additional solution(s)..

FXAA

"Fast Approximate Antialiasing"

- › GPU-based MLAA implementation by Timothy Lottes (Nvidia)
- › Multiple quality options
- › ~1.3 ms/f for 1080p on Geforce 580

Pros & cons:

- › Superb antialiased long edges! 😊
- › Smooth overall picture 😊
- › Reasonably fast 😊
- › Moving pictures do not benefit as much 😞
- › "Blurry aliasing" 😞

Will be released here at GDC'11

- › Part of Nvidia's example SDK



SRAA

"Sub-pixel Reconstruction Antialiasing"

- › Presented at I3D'11 2 weeks ago [Chajdas11]
- › Use 4x MSAA buffers to improve reconstruction

Multiple variants:

- › MSAA depth buffer
- › MSAA depth buffer + normal buffer
- › MSAA Primitive ID / spatial hashing buffer

Pros:

- › Better at capturing small scale detail 😊
- › Less "pixel snapping" than MLAA variants 😊

Cons:

- › Extra MSAA z/normal/id pass can be prohibitive 😞
- › Integration not as easy due to extra pass 😞

GDC 2017 pre-alpha



No antialiasing



4x MSA



4x SRAA, depth-only



4x SRAA, depth+normal





No antialiasing



MSAA Sample Coverage

None of the AA solutions can solve all aliasing

- › Foliage & other alpha-tested surfaces are extra difficult cases
- › Undersampled geometry, requires sub-samples

DX 10.1 added **SV_COVERAGE** as a pixel shader *output*

DX 11 added **SV_COVERAGE** as a pixel shader *input*

What does this mean?

- › We get full programmable control over the coverage mask
- › No need to waste the alpha channel output (great for deferred)
- › We can do partial supersampling on alpha-tested surfaces!



Transparency Supersampling

Shade per-pixel but evaluate alpha test per-sample

- › Write out coverage bitmask
- › MSAA offsets are defined in DX 10.1
- › Requires shader permutation for each MSAA level

Gradients still quite limited

- › But much better than standard MSAA! 😊
- › Can combine with screen-space dither

See also:

- › DirectX SDK 'TransparencyAA10.1
- › GDC'09 STALKER talk [Lobanchikov09]

```
static const float2 msaaOffsets[4] =
{
    float2(-0.125, -0.375),    float2(0.375, -0.125),
    float2(-0.375,  0.125),    float2(0.125,  0.375)
};

void psMain(
    out float4 color : SV_Target,
    out uint coverage : SV_Coverage)
{
    float2 texCoord_ddx = ddx(texCoord);
    float2 texCoord_ddy = ddy(texCoord);

    coverage = 0;

    [unroll]
    for (int i = 0; i < 4; ++i)
    {
        float2 texelOffset = msaaOffsets[i].x * texCoord_ddx;
        texelOffset +=      msaaOffsets[i].y * texCoord_ddy;

        float4 temp = tex.SampleLevel(sampler, texCoord + texelOffset);

        if (temp.a >= 0.5)
            coverage |= 1<<i;
    }
}
```



GDC 2011 test content

Alpha testing



4x MSAA + Transparency Supersampling

Conclusions

DX11 is here – in force

- › 2011 is a great year to focus on DX11
- › 2012 will be a great year for more to drop DX9

We've found lots & lots of quality & performance enhancing features using DX11

- › And so will *you* for your game!
- › Still have only started, lots of potential

Take advantage of the PC strengths, don't hold it back

- › Big end-user value
- › Good preparation for Gen4

Thanks

- › Christina Coffin (@ChristinaCoffin)
- › Mattias Widmark
- › Kenny Magnusson
- › Colin Barré-Brisebois (@ZigguratVertigo)
- › Timothy Lottes (@TimothyLottes)
- › Matthäus G. Chajdas (@NIV_Anteru)
- › Miguel Sainz
- › Nicolas Thibieroz
- › Battlefield team
- › Frostbite team
- › Microsoft
- › Nvidia
- › AMD
- › Intel

Questions?



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Battlefield 3 & Frostbite 2 talks at GDC'11:

Mon 1:45	<i>DX11 Rendering in Battlefield 3</i>	Johan Andersson
Wed 10:30	<i>SPU-based Deferred Shading in Battlefield 3 for PlayStation 3</i>	Christina Coffin
Wed 3:00	<i>Culling the Battlefield: Data Oriented Design in Practice</i>	Daniel Collin
Thu 1:30	<i>Lighting You Up in Battlefield 3</i>	Kenny Magnusson
Fri 4:05	<i>Approximating Translucency for a Fast, Cheap & Convincing Subsurface Scattering Look</i>	Colin Barré-Brisebois



For more DICE talks: <http://publications.dice.se>



References

- › [Lobanchikov09] Igor A. Lobanchikov, "GSC Game World's STALKER: Clear Sky – a showcase for Direct3D 10.0/1" GDC'09.
http://developer.amd.com/gpu_assets/01gdc09ad3ddstalkerclearsky210309.ppt
- › [Lauritzen10] Andrew Lauritzen, "Deferred Rendering for Current and Future Rendering Pipelines" SIGGRAPH'10
<http://bps10.idav.ucdavis.edu/>
- › [Chajdas11] Matthäus G. Chajdas et al "Subpixel Reconstruction Antialiasing for Deferred Shading.". I3D'11